

1. TABULAR DESCRIPTION

POTIX 1K ARRIVAL

Serial number	Path Descriptor	Waypoint Identifier	Fly-over	Course °M(°T)	Magnetic Variation	Distance (km)	Turn Direction	Altitude (m)	Speed limit (km/h)	Nav Spec
010	IF	POTIX	–	–	0	–	–	–	–	RNP 1
020	TF	AGOBI	–	240(240.2)	0	31.13	–	+FL110	–	RNP 1
030	TF	RG815	–	262(262.3)	0	25.87	–	+2150	–	RNP 1
040	TF	RG813	–	256(255.5)	0	21.58	–	+1200	–	RNP 1

TRN 1K ARRIVAL

Serial number	Path Descriptor	Waypoint Identifier	Fly-over	Course °M(°T)	Magnetic Variation	Distance (km)	Turn Direction	Altitude (m)	Speed limit (km/h)	Nav Spec
010	IF	TRN	–	–	0	–	–	–	–	RNP 1
020	TF	AGOBI	–	272(272.0)	0	36.77	–	+FL110	–	RNP 1
030	TF	RG815	–	262(262.3)	0	25.87	–	+2150	–	RNP 1
040	TF	RG813	–	256(255.5)	0	21.58	–	+1200	–	RNP 1

DADEM 1K ARRIVAL

Serial number	Path Descriptor	Waypoint Identifier	Fly-over	Course °M(°T)	Magnetic Variation	Distance (km)	Turn Direction	Altitude (m)	Speed limit (km/h)	Nav Spec
010	IF	DADEM	–	–	0	–	–	@FL110	–	RNP 1
020	TF	OMDES	–	186(185.7)	0	74.08	–	+2150	–	RNP 1
030	TF	RG813	–	225(224.8)	0	33.43	–	+1200	–	RNP 1

KISAN 1K ARRIVAL

Serial number	Path Descriptor	Waypoint Identifier	Fly-over	Course °M(°T)	Magnetic Variation	Distance (km)	Turn Direction	Altitude (m)	Speed limit (km/h)	Nav Spec
010	IF	KISAN	–	–	0	–	–	@FL110	–	RNP 1
020	TF	NISUM	–	142(141.9)	0	51.40	–	+2150	–	RNP 1
030	TF	RG813	–	187(186.6)	0	17.66	–	+1200	–	RNP 1

2. HOLDING PROCEDURES

Holding Fix	Inbound Course °M(°T)	Magnetic Variation	Time (min)	Turn Direction	Altitude (m)	Speed limit (km/h)	Nav Spec
AGOBI	262(262.0)	0	1 ≤ FL140 1.5 > FL140	R	+FL110	-425 ≤ FL140 -445 > FL140	RNP 1
OMDES	225(225.0)	0	1 ≤ FL140 1.5 > FL140	R	+2150	-425 ≤ FL140 -445 > FL140	RNP 1
NISUM	187(187.0)	0	1 ≤ FL140 1.5 > FL140	R	+2150	-425 ≤ FL140 -445 > FL140	RNP 1
RG813	165(165.0)	0	1 ≤ FL140 1.5 > FL140	R	+1200	-425 ≤ FL140 -445 > FL140	RNP 1